

**Propositions**

attached to the thesis

**Truck Platooning**  
**Planning and Behaviour**

Anirudh Kishore Bhoopalam  
Erasmus University Rotterdam  
XXXXXX 2021

## I

Platoon plans for trucks are beneficial only if drivers adhere to them.

*(This Thesis)*

## II

Planning for a truck to join multiple platoons along its route requires significant computing power.

*(Chapters 2 and 3)*

## III

2-truck platoons where each truck can join at most one platoon achieve most of the platooning benefits.

*(Chapter 3)*

## IV

Smartly combining network designs generated using different sets of scenarios can create designs that perform as well as those generated using all the scenarios together.

*(Chapter 4)*

## V

Truck drivers tend to be skeptical about technology that interferes with their driving task; including platooning.

*(Chapter 5)*

## VI

Platooning will be an invaluable test case for autonomous driving on public roads.

## VII

What automation does to societal inequality depends on how it is implemented.

*(Inspired by Stephen Hawking)*

## VIII

The goal of a first draft is not to write something good but to write something down.

## IX

To know happiness, you must know sadness.

## X

Simplicity is a great virtue but it requires hard work to achieve it and education to appreciate it. And to make matters worse: complexity sells better.

*(Edsger Wybe Dijkstra)*

## XI

Change is good.

*(Rafiki)*